27/03/25



CHERI in SoC

Working Group Update

Ben Fletcher Working Group Lead – CHERI Alliance



- What is the working group's mission?
- Current Activities and Status



• What is the working groups mission ?

- The CHERI in SoC Working Group focuses on defining and standardising what needs to be included in a system to support CHERI.
 - We want to make it easier for people to build CHERI technology into their systems.
 - Explain the complexities and challenges of integrating CHERI technology into a system.



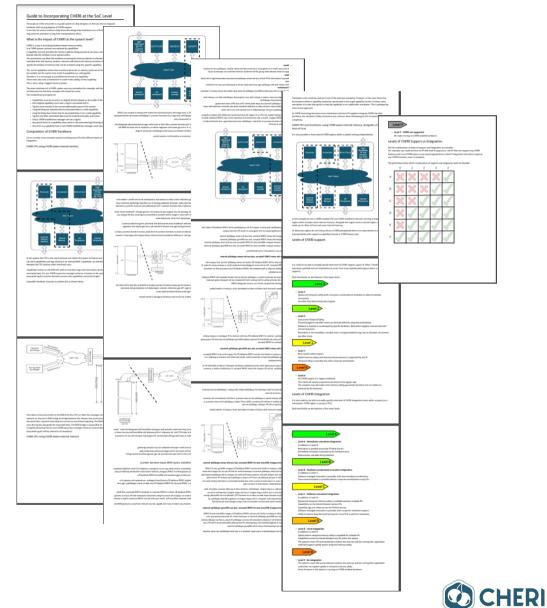
O Current Activities and Status

- We have written some material to help guide people into the world of building CHERI systems.
 - Our guide is a starting point, which assumes no prior CHERI knowledge.
- As part of the guide, we have proposed different levels of CHERI support, for both IP and systems:
 - To guide IP and system developers.
 - To aid comparison and selection of IP and systems.



Guide to Incorporating CHERI at the SoC Level

- Developed by working group.
- Received both internal and external review to the working group.
- Already used with 2 external IP companies to assist with CHERI ramp-up.
 - Available on github:
 - https://github.com/CHERI-Alliance/ SoC-System-WG/blob/main/ guidance.md



O 4 levels of IP Support

• Level 0:

- No CHERI support
- Note that the compiler may still be able to make some memory-safety guarantees.



Level 3:

Spatial and temporal safety (with revocation accelerated via hardware to allow immediate revocation).

Use-after-free deterministically trapped.



Level 2:

Concurrent Temporal Safety.

Protecting against use-after-reuse can be done without a stop-the-world phase.

Software is assisted or accelerated by specific hardware. Revocation happens concurrently with normal execution.

Revocation is not immediate, use after free is *not* guaranteed to trap, but an allocator can prevent use after reuse.



Level 1:

Basic spatial safety support.

Spatial memory safety with bounds and permissions is supported by the IP. Temporal safety is possible only with a stop-the-world phase.



· Level 0:

No CHERI support (i.e. legacy hardware).

This means all memory operations are done in the regular way.



○ 4 levels of IP Support

• Level 1:

- Basic spatial memory safety.
- Temporal safety is only possible with a stop-theworld phase.



Level 3:

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Level 0:

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This means all memory operations are done in the regular way.



O 4 levels of IP Support

• Level 2:

- Concurrent temporal safety.
- Revocation happens concurrently with normal execution but is *not* immediate.
- Use-after-free is not guaranteed.
- An allocator can prevent use-after-reuse.



Level 3:

Spatial and temporal safety (with revocation accelerated via hardware to allow immediate revocation).

Use-after-free deterministically trapped.



Level 2:

Concurrent Temporal Safety.

Protecting against use-after-reuse can be done without a stop-the-world phase.

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Level 1:

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Level 0:

No CHERI support (i.e. legacy hardware).

This means all memory operations are done in the regular way.



O 4 levels of IP Support

• Level 3:

- Spatial and Temporal memory safety.
- Revocation is immediate.
- Use-after-free deterministiclly trapped.



Level 3:

Spatial and temporal safety (with revocation accelerated via hardware to allow immediate revocation).

Use-after-free deterministically trapped.



Level 2:

Concurrent Temporal Safety.

Protecting against use-after-reuse can be done without a stop-the-world phase.

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Level 1:

Basic spatial safety support.

Spatial memory safety with bounds and permissions is supported by the IP. Temporal safety is possible only with a stop-the-world phase.



Level 0:

No CHERI support (i.e. legacy hardware).

This means all memory operations are done in the regular way.



• Level F:

- CHERI is not supported



 Level A - Immediate revocation integration: In addition to Level B: Revocation is possible across the IP-block barrier. Immediate revocation is possible at the hardware level. Deterministic use-after-free protection.



 Level B - Hardware accelerated revocation integration: In addition to Level C: Software managed revocation is possible, with some hardware acceleration.

Concurrent revocation is possible without a stop-the-world phase on any IPs



 Level C - Software revocation integration: In addition to Level D: Spatial and temporal memory safety is available between multiple IPs. Capabilities can be shared between various IPs. Capability tags are visible across the IP-block barrier. Software managed revocation is possible, with no specific hardware support. Likely to need to stop-the-world (at least for some IPs) to perform revocation.



Level D - Local integration:

In addition to Level E:

Spatial and/or temporal memory safety is available for isolated IPs.

Capabilities cannot be shared between any IPs within the system.

The system's main CPU and accelerators (where the end user will be running their application code) will support spatial and/or temporal memory safety.



Level E - No integration:
The system's main CPU and accelerators (where

The system's main CPU and accelerators (where the end user will be running their application code) does not support spatial or temporal memory safety. Some firmware in the system is runnine on CHERI enabled hardware.

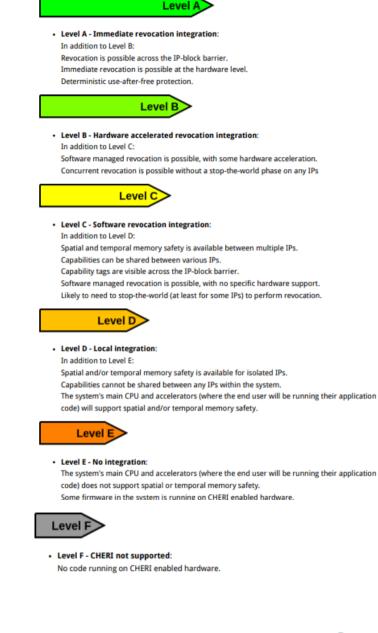


 Level F - CHERI not supported: No code running on CHERI enabled hardware.



• Level E:

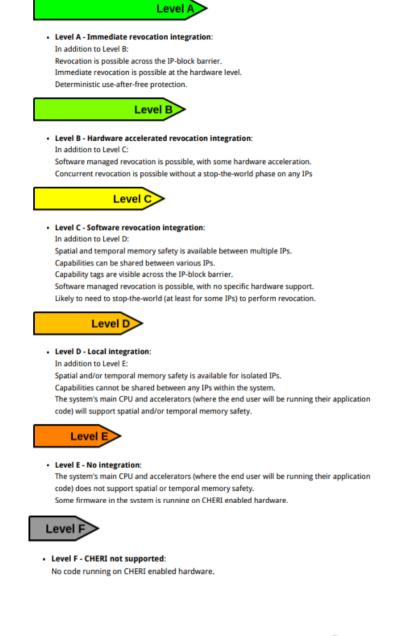
- System's main CPU and accelerators do *not* support CHERI.
- Some code on the system is running on CHERI enabled hardware.





• Level D:

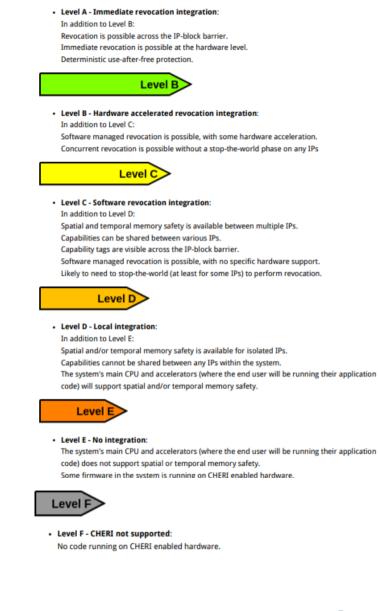
- System's main CPU and accelerators do support CHERI.





• Level C:

- Capabilities (and tags) can be shared between multiple IPs.
- Revocation performed using a stop-the-world phase.

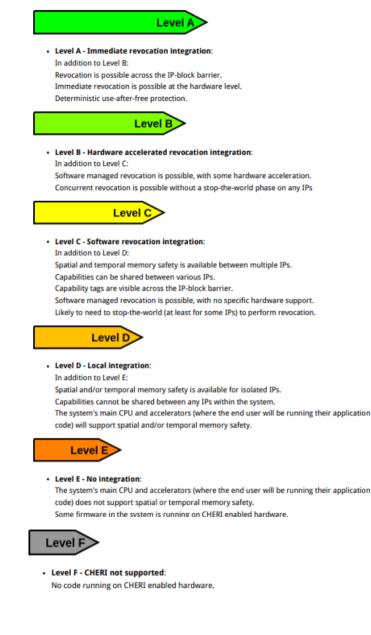


Level /



• Level B:

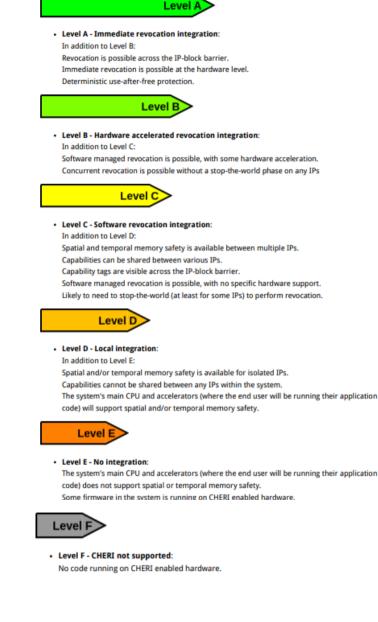
 Concurrent revocation is possible without a stop-theworld phase on any IPs.





• Level A:

- Revocation is possible across the IP-block barrier.
- Immediate revocation is possible at the hardware level.
- Deterministic use-after-free protection.







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